

Motivation

Solve f(g(x)),arg min $x \in \{0,1\}^k, g(x) \in \mathcal{S}$ $f(g(x)) = \langle g(x), \mathbf{Q}g(x) + \mathbf{c} \rangle,$ for some feasible set $S \subset \mathbb{R}^n$.



(a) Minimise f(g(x))f quadratic in g(x): \checkmark , x binary: \checkmark , g linear in x: \checkmark AQC: 7 Not a QUBO

From Discrete to Quantum

- **Challenge:** Problem (1) is a discrete problem.
- Idea: Could be tackled on quantum annealer.
- **Challenge:** Problem (1) is not a QUBO.



f quadratic in $g^t(x)$: \checkmark , x binary: \checkmark , g^t linear in x: \checkmark AQC:
Iteratively solve QUBOs



Example Applications

Shape matching:

 $\|\mathbf{AP} - \mathbf{PB}\|_F^2$ arg min

where **P** can be expressed as a function of binary variables.

Point set registration:

 $\|\mathbf{X}\mathbf{P}-\mathbf{R}\mathbf{Y}\|_{F}^{2},$ arg min $\mathbf{R} \in SO(d), \mathbf{P} \in \Pi_n$ where **R** and **P** can be expressed as functions of binary variables.

Adiabatic Quantum Computing (AQC)

Quantum annealers can solve Quadratic Unconstrained Binary Optimisation (QUBO) problems:

 $\langle x, \mathbf{Q}x + \mathbf{c} \rangle$, arg min

where $\langle \cdot, \cdot \rangle$ is the standard inner product in \mathbb{R}^n , **Q** a symmetric matrix, and **c** a vector [1].



They rely on the Schrödinger equation $i\hbar \frac{\partial |\psi(t)\rangle}{\partial t} = H(t) |\psi(t)\rangle,$ $H(t) = -(1 - \frac{t}{\pi})$

Adiabatic theorem: If t varies slowly enough, the evolution of the system will instantaneously keep the state $|\psi(t)\rangle$ into the ground state $|E_0(t)\rangle$ of H(t), which is at t = T the solution of the QUBO.

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QuCOOP: A Versatile Framework for Solving Composite and Binary-Parametrised Problems on Quantum Annealers

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(SM)

(PSR)

(3)

$$, t \in [0, T],$$
 (4)

$$Q_{ij}\sigma_i^z \otimes \sigma_j^z + \sum_{i=1}^n c_i\sigma_i^z\right)$$

 $=:H_p$

QuCOOP: COmposite OPtimisation on QUantum Annealers

Algorithm

Initialize x^0 and repeat for t = 0, 1, 2, ... $g^{t}(x) := g(x^{t}) + \left\langle \nabla g(x^{t}), x - x^{t} \right\rangle$

$$x^{t+1} \leftarrow \underset{x \in \mathbb{B}^{k}}{\operatorname{arg\,min}} \left\{ f^{t}(x) := f(g^{t}(x)) \right\} (6)$$

s.t. $g^{t}(x) \in \mathcal{S}$ (7)

Application to Shape Matching and Point set Registration

Binary parametrisation of permutations: Any permutation matrix $\mathbf{P} \in \Pi_n$ can be parametrised with a length-k, k = n(n-1)/2, binary vector $x := (x_1, \ldots, x_k)$ via the function

 $\mathbf{P}(x) := \prod \mathbf{P}_i(x_i)$

where $\mathbf{T}_{i}^{x_{i}}$ is the *i*th transposition from ((a, b), a, b = 1, ..., n, a < b) if $x_{i} = 1$ and $\mathbf{I}_{n \times n}$ otherwise.

Illustration:

 $(c,d,b,a)
ightarrow (\mathbf{a},d,b,c)
ightarrow$

Fix position 2 Fix position 1 Transpose (1, 4) Transpose (2, 3) Transpose (3, 4)

$$\mathbf{P} = (3,4)^1 \cdot (2,4)^0 \cdot (2,3)^1 \cdot (1,4)^1 \cdot (1,3)^0 \cdot (1,2)^0$$

Binary parametrisation of rotations: Any rotation matrix in SO(d) can be parametrised as

$$\mathbf{R}(y) = \exp(\mathbf{M}(y)), \quad \mathbf{M}(y) = \begin{pmatrix} 0 & -y \\ y & 0 \end{pmatrix} \text{ in } 2\mathbf{D}, \quad \mathbf{M}(y) = \begin{pmatrix} 0 & -y_3 & y_2 \\ y_3 & 0 & -y_1 \\ -y_2 & y_1 & 0 \end{pmatrix} \text{ in } 3\mathbf{D}.$$
(9)

Trick: Write $y_i = a \cdot \sum_i 2^i q_i$, $q_i \in \{0, 1\}$ and refine discretisation interval: [+++] \rightarrow []]++]

QuCOOP as Applied to SM and PSR

Set
$$\mathbf{p}(x^t) + \langle \nabla \mathbf{p}(x^t), x - x^t \rangle$$
 and $\mathbf{r}^t(y) = \mathbf{r}(y^t) + \langle \nabla \mathbf{p}(x^t), x - x^t \rangle$

$$(SM) \Leftrightarrow \underset{x \in \{0,1\}^k}{\operatorname{arg\,min}} \langle g^t(x), \mathbf{Q}g^t(x) \rangle + \Box, \qquad (PSR) \Leftrightarrow \underset{(x,y) \in \{0,1\}^k}{\operatorname{arg\,min}} \langle g^t(x,y), \mathbf{Q}g^t(x,y) \rangle + \Box, \mathbf{Q} := \alpha \mathbf{I}_{n \times n} - \mathbf{A} \otimes \mathbf{B}, \qquad (PSR) \Leftrightarrow \underset{(x,y) \in \{0,1\}^k}{\operatorname{arg\,min}} \langle g^t(x,y), \mathbf{Q}g^t(x,y) \rangle + \Box, \mathbf{Q} := \begin{pmatrix} \alpha \mathbf{I}_{n \times n} & -\frac{1}{2}\mathbf{X} \otimes \mathbf{Y} \\ -\frac{1}{2}(\mathbf{X} \otimes \mathbf{Y})^\top & \beta \mathbf{I}_{d \times d} \end{pmatrix},$$

$$\mathbf{Q} := \alpha \mathbf{I}_{n \times n} - \mathbf{A} \otimes \mathbf{B},$$

With
$$g^t(x) =: \mathbf{p}^t(x)$$
 in (SM), $g^t(x, y) := (\mathbf{p}^t(x), \mathbf{r})$

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Equivalent QUBO

In each iteration t, solve arg min $\langle x, \mathbf{Q}^t x + \mathbf{c}^t \rangle$ + PenaltyTerm $(g(x^t))$, $x \in \{0,1\}^k$ $\mathbf{Q}^t := \nabla g(x^t) \mathbf{Q} \nabla g(x^t)^\top,$ $\mathbf{c}^t := \nabla g(x^t) \left[\mathbf{c} + 2\mathbf{Q} \left[g(x^t) - \nabla g(x^t)^{\mathsf{T}} x^t \right] \right].$

$$\mathbf{P}_i(x_i) := \mathbf{T}_i^{x_i}, \qquad (8)$$

Done

$$(\mathbf{a}, \mathbf{b}, d, c) \rightarrow (\mathbf{a}, \mathbf{b}, \mathbf{c}, \mathbf{d})$$

Fix position 3

$$\begin{array}{c} t+1\\ i \\ y_i^t \end{array} \qquad y_i^t \end{array}$$

 $\langle \nabla \mathbf{r}(y^t), y - y^t \rangle$. In each iteration t:

 $\mathbf{r}^{t}(y)$ in (PSR) and $\Box := \alpha \cdot ||(g^{t}(\cdot))||^{2}, \ \alpha \in \mathbb{R}_{+}$.

I. Shape Matching using Simulated Annealing (vs. Q-Match [3])







Summary:





Results

• QuCOOP extends the scope of AQC to some form of non-quadratic problems, see Problem (1). QuCOOP is able to handle problems involving permutations/assignments.

• QuCOOP is versatility and compatibility with continuous problems such as in (PSR).

References

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